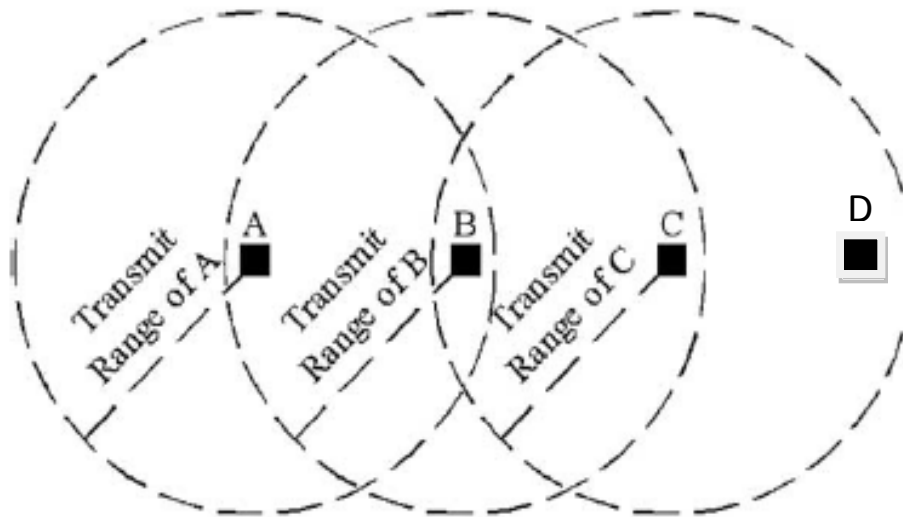


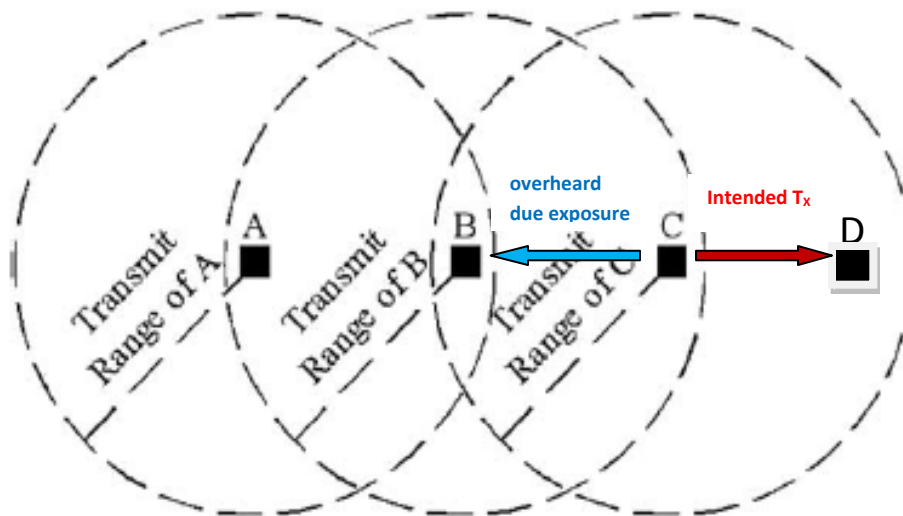
# Hidden/Exposed stations problems in CSMA-MAC: (H/ESP)

Hidden Terminal Problem: ([www.cs.virginia.edu/~cs851-2/course.htm](http://www.cs.virginia.edu/~cs851-2/course.htm))



- Node B can communicate with A and C both
- A and C cannot hear each other
- When A transmits to B, C cannot detect the transmission using the carrier sense mechanism
- If C transmits to D, collision will occur at B

Exposed Terminal Problem: ([www.cs.virginia.edu/~cs851-2/course.htm](http://www.cs.virginia.edu/~cs851-2/course.htm))



- 
- Node C can communicate with B and D both
  - Node B can communicate with A and C
  - Node A cannot hear C
  - Node D cannot hear B
  - When C transmits to D, B detects the transmission using the carrier sense mechanism and postpone to transmit to A, even though such transmission will not cause collision (B can Tx while receiving, but not receiving two or more at the same time). We say that B is exposed to C's traffic and stopped Tx, wasting Bandwidth.

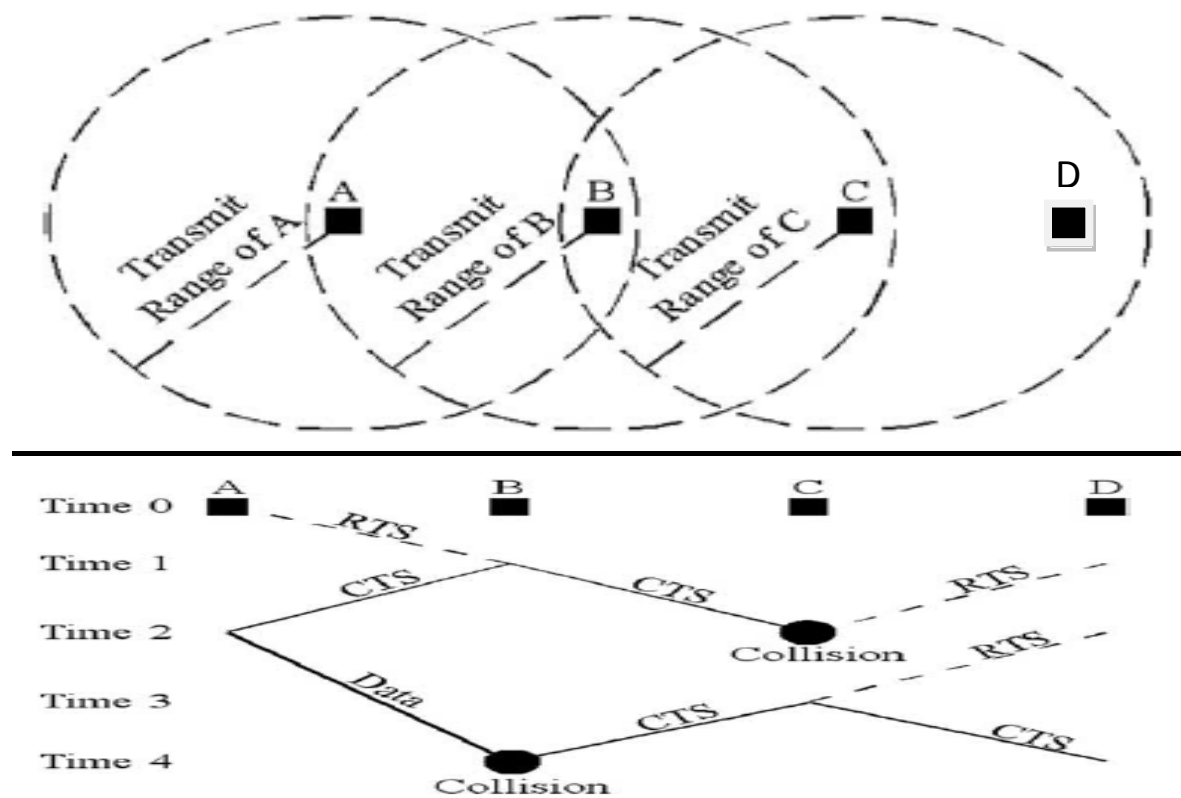
**Partial Solution:** Multiple Access Collision Avoidance MACA (1, 2, and 4 only)  
 & MACA for Wireless (MACAW) (1-to-5)

Stations A&B communicate, via the following sequence of handshaking steps:

1. “Request To Send” frame (**RTS**) from A to B. (All A’s neighboring stations are going to sleep for the session duration which is included in the RTS control frame) (Problem?!?! YES. WHY?!?!?) Assume node Y only with range of A, hears A’s RTS to B, then blocks for the duration, which is unfair to Y in case of B never answers!
2. “Clear To Send” frame (**CTS**) from B to A. (All B’s neighboring stations are going to sleep for the session duration which is included in the CTS control frame)
3. “Data Sending” frame (**DS**) from A to B. (All neighboring stations are going efficiently to sleep for the session duration which is included in the control frame) [NOT in MACA]
4. **DATA** fragment frame from A to B, and (All detecting stations sleeps until ACK+ small random time)
5. Acknowledgement frame (**ACK**) from B to A. (all sleeping stations wakeup).

Now, when A transmits RTS to B, B will respond by CTS to A, which will be overheard by C. Hence, C will sleep on its own initialized NAV (CTS includes the time duration of the sleep), NO collision scenario as before in CSMA above!! (Really?!)

MACA failed to handle the Hidden Station problem:



Hidden terminal problem after using RTS/CTS control packets

( paper.ijsns.org/07\_book/201010/20101020.pdf)

1. A wants to send **data** packet to B.
2. A sends **RTS** to B.
3. Upon receiving the **RTS**, B sends CTS to A, but C gets it too.
4. At the same time D sends **RTS** to C for transmitting data packet, which **collides** with B's **CTS** at C.
5. After receiving **CTS** from B, A transmits data to B and D times out and resends **RTS** to C.

6. When *C* gets the resubmitted *D*'s **RTS** (no collision this time), *C* sends **CTS** to *D*, but *B* gets it anyway (wireless broadcast medium) while still receiving **data** from *A*, hence **collision** at *B*!!!

Does MACA fail also to handle the Exposed Station problem????!! (left for you to research!!)

Hence IEEE802.11 MAC defines **two** modes:

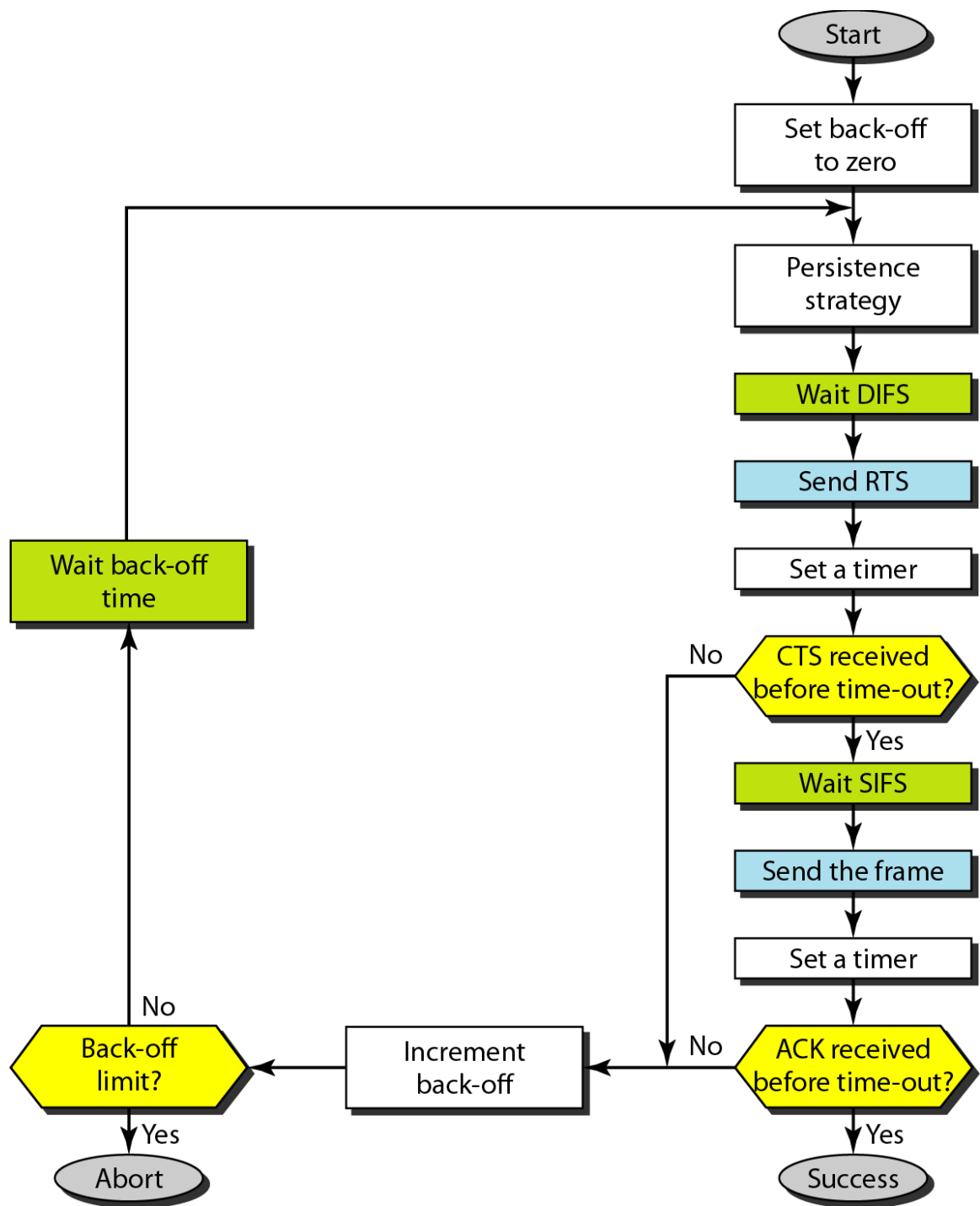
1. **DCF (Distributed Coordination Function) & PCF (Point Coordination Function)**
2. **DCF is based on CSMA + MACAW+ NAV**

- ✚ 4 steps handshaking (Virtual CS): RTS-CTS-DATA-ACK
- ✚ **Physical CS + Virtual CS via the NAV (network allocation vector) containing time value that all overhearing station will await on (as obtained next) until medium is free again.**
- ✚ **Every of the above handshaking control packets contains the time duration **remaining** in the communication session.**
- ✚ **NAV is continuously updated via any new *overhearing*.**

➤ **IFS (inter frame spacing)**

- **Short IFS (SIFS), PCF IFS (PIFS), DCF IFS (DIFS), Extended IFS (EIFS)**

The **IEEE802.11 MAC' DCF** combines CSMA & MACAW+NAV (**Network Allocation Vector**) counter for other noninvolved stations (neighbors of A&B) to await on! (for **Virtual Sensing**)



### IEEE802.11 MAC (DCF) [ad-hoc]Protocol

It is a mix of CSMA & MACAW with NAV (virtual sensing).